

16 (c) pivoting manually a wrist-pivoting element of the
17 control assembly to cause the wrist member of pivot
18 correspondingly about the distal forearm end and along the first
19 axis of step (a); and

20 (d) moving manually an end effector-controlling
21 element of the control assembly to cause the end effector member
22 to move about the second axis of step (a) and perform a surgical
23 procedure at the internal surgical site within the anatomy of the
24 person.

Claim 64, line 2, delete "assembly" and substitute
therefor --member--.

Claim 65, line 2, delete "assembly" and substitute
therefor --member--.

Claim 78, lines 3 and 5, delete "such" and substitute
therefor --in a manner--.

Claim 85, lines 3 and 5, delete "systems" and
substitute therefor --system--.

Claim 85, line 4, delete "control" and substitute
therefor --station--.

Claim 86, lines 3 and 5, delete "systems" and
substitute therefor --system--.

Claim 86, line 4, delete "control" and substitute
therefor --station--.

Please add the following claims:

104. A method for performing surgery on an anatomy of a
person comprising the acts of:

providing a control assembly coupled to a surgical
assembly comprising a surgical instrument including a forearm
member having a distal forearm end, a wrist member pivotally
connected to the distal forearm end of the forearm member in a
manner as to be capable of being pivoted about a first axis, and
an end effector member movably coupled to the wrist member in a
manner as to be capable of being moved about a second axis that
is generally perpendicular to the first axis;